# **6.100B: Recitation 6** Classifiers: Perceptron and Neural Networks

May 12th, 2023

### Actionables

PS4 checkoff is due today, 5/12 by 5pm

PS5 due on Monday, 5/15 by 9pm; no Checkoff!

No office hours on or after **Tuesday**, **5/16** 



### **Classification** Hyperplanes Perceptron Neural Networks

### Let's get started!

We've already dealt with Machine Learning through linear regressions to create a model to fit data while still being generalizable

What about data with more dimensionality?

dimensionality

- When we would like to **classify** data, we need to create a model that can be trained to predict a quality of a sample based on its

When dealing with 2D Space, a **hyperplane** is a line that



# separates space into a **positive** domain and a **negative** domain

We can represent our model as a hypothesis:

$$y = 1 \text{ if } \theta^{\mathsf{T}} x + \theta_0 > 0$$

y = -1 otherwise

$$\begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix}^{\top} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \theta_0 = \theta_2 x_2 + \theta_1 x_1 + \theta_0$$





For example, let's consider a point (2,5) on the coordinate plane

A model with  $\theta = [1, -3]$  and  $\theta_0 = 2$  will classify this point:



Therefore, this point would be classified as y = -1

Given a cluster of data in which **Blue** represents a positive do we create a model to fit the data?



classification and **Red** represents a negative classification, how

regression, only we're concerned now with **classifying points correctly**, rather than how far we are from the point

Therefore, we only assign loss when we **misclassify** a point

$$J(\theta, \theta_0) = -\sum_{i}^{N} \left( y_i(\theta^{\mathsf{T}} x_i + \theta_0) \right)$$
  
Otherwise,  $J(\theta, \theta_0) = 0$ 

This loss function is called the **hinge loss** 

- Our objective function will follow roughly the same idea as our linear

the right direction:



prediction:

If our model is wrong, we want to ensure that our model steps in

$$\sum_{i}^{N} \left( y_i (\theta^{\mathsf{T}} x_i + \theta_0) \right)$$

This way, we correct each attribute of our model in the following way when the model finds a mistake, y is the same sign as our

This way, we correct each attribute of our model in the following way when the model finds a mistake, **y** is the same sign as our prediction:

 $\theta_2 := \theta_2 + \theta_2$ 

 $\theta_1 := \theta_1 +$ 

 $\theta_0 :=$ 

Where  $y_j$  represents one of R misclassified points. We **accumulate the error** in each epoch before making our step, though this strategy can be altered to our needs

$$\frac{1}{N} \sum_{j}^{R} (y_j)(x_j[2])$$

$$\frac{1}{N} \sum_{j}^{R} (y_j)(x_j[1])$$

$$\theta_0 + \frac{1}{N} \sum_{j}^{R} y_j$$







same data for too many epochs

coordinate plane)

As  $\|\theta\|$  grows, it becomes harder to train when introduced to new data

How do we dissuade this behavior?

# Our model will overfit our data **very quickly** when training on the

### With hyperplanes, each dimension $\theta_i$ can grow very large while preserving the same linear discriminator (the plane dividing our 2D

Many different strategies, but a popular one is a regulating term

$$J(\theta, \theta_0) = -\frac{1}{N} \sum_{i}^{N} \left( y_i(\theta^\top x_i + \theta_0) \right) + \frac{1}{2} \lambda \|\theta\|^2$$

In this case, we can continuously train our model to stay as **simple as possible** while correcting our hyperplane classifier if we misclassify a point.

In this case, we can continuously train our model to stay as **simple as possible** while correcting our hyperplane classifier if we misclassify a point:



We don't regularize the bias because data that isn't centered at 0 may need a large bias to avoid underfitting.

 $\theta_0 :=$ 

$$\left[ \frac{1}{N} \sum_{j}^{R} (y_j)(x_j[2]) \right] - \lambda \theta_2$$

$$\left[ - \frac{1}{N} \sum_{j}^{R} (y_j)(x_j[1]) \right] - \lambda \theta_1$$







With our new regulating term in our objective function, controlled by  $\lambda \in [0,1]$ , our final model after 9 epochs has a **smaller magnitude**  $\theta$ !

This prevents overfitting, and makes our model simpler to achieve this feature

# Machine Learning | Perceptron

the earliest linear classifiers, and the precursor to Neural Networks



# What we've just implemented is known as **Perceptron**, one of

## Machine Learning | Perceptron

# The **Perceptron** has a certain **input dimensionality**, as well as an **output dimensionality**





# Machine Learning | Neural Networks

# dimensionality than the input as well:



Neural Layers in networks can produce a more complex output

# Machine Learning Neural Networks

of **several** different model attributes or **weights**, not just  $\theta$ 



# Each connection has its own weight, leading to the requirement

# Machine Learning | Neural Networks

These computations end up being most easily computed using **matrix multiplication**, storing the weights of each layer in a weight matrix mapping input dimensionality to output dimensionality  $W_{i\times o}$ 

For an input dimensionality of 3 and an output dimensionality of 1, our weight matrix:

$$W_{3\times 1} = \begin{bmatrix} w_{1,1} \\ w_{2,1} \\ w_{3,1} \end{bmatrix}$$



# Machine Learning | Neural Networks

Neural Networks end up being several **layers** of modified



# Perceptrons, with an output layer that can classify items for us!

# Machine Learning Clustering

we'd like to classify non-linearly discriminable data using models with less complexity



# Though Neural Networks can modify the dimensionality of our information between layers, there are certain cases in which

# Machine Learning | Clustering

**KNN** or (**K-Nearest-Neighbors**) is a means of classification in which we predict a data point's classification based on the classification of **K** data points that are spatially closest to it

To determine what we can classify a point  $x_i$  as, we need to rank our other datapoints by distance to  $x_i$  and choose the majority label

