# **6.100B: Recitation 6** Classifiers: Perceptron and Neural Networks

May 12th, 2023

### **Actionables**

**PS4 checkof** is due **today, 5/12** by **5pm**

**PS5 due** on **Monday, 5/15** by **9pm**; no Checkoff!

No office hours on or after **Tuesday, 5/16**



### **Classification** Hyperplanes Perceptron Neural Networks

### **Let's get started!**

We've already dealt with Machine Learning through linear regressions to create a model to fit data while still being generalizable

What about data with more dimensionality?

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- When we would like to **classify** data, we need to create a model that can be trained to predict a quality of a sample based on its

dimensionality

When dealing with 2D Space, a **hyperplane** is a line that



# separates space into a **positive** domain and a **negative** domain

We can represent our model as a **hypothesis:**

$$
y = 1 \text{ if } \theta^{\mathsf{T}} x + \theta_0 > 0
$$

*y* = −1 otherwise

$$
\begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix}^\top \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \theta_0 = \theta_2 x_2 + \theta_1 x_1 + \theta_0
$$





For example, let's consider a point  $(2,5)$  on the coordinate plane

A model with  $\theta = [1, -3]$  and  $\theta_0 = 2$  will classify this point:

Therefore, this point would be classified as **y = -1**



Given a cluster of data in which **Blue** represents a positive do we create a model to fit the data?



classification and **Red** represents a negative classification, how

- Our objective function will follow roughly the same idea as our linear
	-

regression, only we're concerned now with **classifying points correctly**, rather than how far we are from the point

Therefore, we only assign loss when we **misclassify** a point

This loss function is called the **hinge loss**

$$
J(\theta, \theta_0) = -\sum_{i}^{N} (y_i(\theta^\top x_i + \theta_0))
$$
  
Otherwise,  $J(\theta, \theta_0) = 0$ 

the right direction:

This way, we correct each attribute of our model in the following way when the model finds a mistake, **y** is the same sign as our

prediction:

If our model is wrong, we want to ensure that our model steps in



$$
-\sum_{i}^{N}\left(y_{i}(\theta^{\top}x_{i}+\theta_{0})\right)
$$

This way, we correct each attribute of our model in the following way when the model finds a mistake, **y** is the same sign as our prediction:

 $\theta_2 := \theta_2 +$ 

 $\theta_1 := \theta_1 +$ 

 $\theta_0 := \theta$ 

Where  $y_j$  represents one of  $R$  misclassified points. We  $\rm{accumulate}$  the  $\rm{error}$  in each epoch before making our step, though this strategy can be altered to our needs

$$
\frac{1}{N} \sum_{j}^{R} (y_j)(x_j[2])
$$
  

$$
\frac{1}{N} \sum_{j}^{R} (y_j)(x_j[1])
$$
  

$$
\theta_0 + \frac{1}{N} \sum_{j}^{R} y_j
$$







# Our model will overfit our data **very quickly** when training on the

same data for too many epochs

### With hyperplanes, each dimension  $\theta_i$  can grow very large while preserving the same linear discriminator (the plane dividing our 2D

As  $\|\theta\|$  grows, it becomes harder to train when introduced to new data

coordinate plane)

How do we dissuade this behavior?

Many different strategies, but a popular one is a **regulating term**

In this case, we can continuously train our model to stay as we misclassify a point.

**simple as possible** while correcting our hyperplane classifier if

$$
J(\theta, \theta_0) = -\frac{1}{N} \sum_{i}^{N} (y_i(\theta^\top x_i + \theta_0)) + \frac{1}{2} \lambda ||\theta||^2
$$

In this case, we can continuously train our model to stay as **simple as possible** while correcting our hyperplane classifier if we misclassify a point:

We don't regularize the bias because data that isn't centered at 0 may need a large bias to avoid underfitting.

 $\theta_0 :=$ 



$$
\sum_{j}^{R} (y_j)(x_j[2]) - \lambda \theta_2
$$
\n
$$
\sum_{j}^{R} (y_j)(x_j[1]) - \lambda \theta_1
$$
\n
$$
\theta_0 + \frac{1}{N} \sum_{j}^{R} y_j
$$







This prevents overfitting, and makes our model simpler to achieve this feature

# **Machine Learning |** Hyperplanes

With our new regulating term in our objective function, controlled by  $\lambda \in [0,1]$ , our final model after 9 epochs has a **smaller magnitude θ!** 

# What we've just implemented is known as **Perceptron**, one of

the earliest linear classifiers, and the precursor to Neural Networks



# **Machine Learning |** Perceptron

### The **Perceptron** has a certain **input dimensionality**, as well as an **output dimensionality**

## **Machine Learning |** Perceptron





Neural **Layers** in networks can produce a more complex **output** 

# **Machine Learning | Neural Networks**

# **dimensionality** than the input as well:



# Each connection has its own **weight**, leading to the requirement

# **Machine Learning | Neural Networks**

of **several** different model attributes or **weights**, not just *θ*



# **Machine Learning | Neural Networks**

These computations end up being most easily computed using **matrix multiplication**, storing the weights of each layer in a weight matrix mapping input dimensionality to output dimensionality  $W_{i \times o}$ 

For an input dimensionality of 3 and an output dimensionality of 1, our weight matrix:



$$
W_{3\times 1} = \begin{bmatrix} w_{1,1} \\ w_{2,1} \\ w_{3,1} \end{bmatrix}
$$

Neural Networks end up being several **layers** of modified



# Perceptrons, with an output layer that can **classify items** for us!

# **Machine Learning |** Neural Networks

# Though Neural Networks can modify the dimensionality of our information between layers, there are certain cases in which

we'd like to classify **non-linearly discriminable data** using models with less complexity



# **Machine Learning |** Clustering

**KNN** or (**K-Nearest-Neighbors**) is a means of classification in which we predict a data point's classification based on the classification of **K** data points that are spatially closest to it

To determine what we can classify a point  $x_i$  as, we need to rank our other datapoints by distance to  $x_i$  and choose the majority label



# **Machine Learning |** Clustering