### **6.100B: Recitation 5** Regressions, Overfitting, & Machine Learning

May 5th, 2023

#### **Actionables**

**PS3 Checkoff** due at **5pm** today

**PS4 Checkof** start today, due on **Friday, 5/12** at **5pm**

**Microquiz 4** on **Wednesday, 5/10** in-class



#### **Curve Fitting** Linear Regressions R2 Overfitting

#### **Machine Learning** Training / Testing Datasets Evaluation

#### **Let's get started!**

#### **<https://mattfeng.tech/teaching/6.100B>**

- The purpose behind curve-fitting is to take **data we have** and
- We can then use that **trend** to predict the nature of a system
- It is an important way of mathematically creating and optimizing

generalize it to a hypothesized **trend**

**hypotheses** based on data we're collecting

Anscombe's Quartet is an example of the significance of

# graphical analysis in producing generalizable models for data





Each graph depicts a linear regression of the data in orange that minimizes our mean squared error (MSE)

How can we generate **general models** for fitting data?

# We'll think about this problem by asking **how do we minimize**

**the error between our predictions and reality?**



Given a linear regression with a **single input variable** and a **error**:

# **single output variable**, there exists a curve that minimizes **the**



$$
f(x) = \sum_{i}^{\infty} c_i x^i
$$

Or if we ignore terms  $i > 1$  (linear fit):

 $f(x) = c_1 x + c_0$ 

What exactly are we minimizing? How do we choose coefficients

A more informative measurement of a model's fit is actually R $^2$ ,  $\,$ 

sum squared regression (SSR)

#### **Curve Fitting | Linear Regressions**

- $c_1$  and  $c_0$ ?
- We are looking to minimize the **error**, or **loss function**
- or the **Coefficient of Determination**

total sum of squares (SST)

 $R^2 = 1 - \frac{\text{sum squared regression (SSR)}}{1 - \frac{\text{sum of the total}}{1 - \frac{\text{max of the total}}{1 - \frac{\$ 

 $R^2 = 1 -$ 

#### Where  $\hat{y}_i$  is our **predicted value** for input  $i$ , and  $\bar{y}$  is our **average output** ̂

total sum of squares (SST)

$$
\frac{\sum_{i}^{n}(y_{i}-\hat{y}_{i})^{2}}{\sum_{i}^{n}(y_{i}-\bar{y})^{2}}
$$

We can see that maximizing  $R^\angle$  means **minimizing the SSR** *R*2

SSR is the **mean squared error** of our sample batch:

 $SSR =$ 

$$
\sum_{i}^{n} (y_i - \hat{y}_i)^2
$$



(observed[*i*] − predicted[*i*]) 2

We can define our **objective function** (also called a **loss function**) we'd like to **minimize** as our SSR divided by the

> $J(c) =$ 1 *N*

# number of samples to effectively minimize our **per sample error**

Or for our linear model:

 $J(c_1, c_0) =$ 

$$
\frac{1}{N} \sum_{i}^{N} (y_i - \hat{y}_i)^2
$$

$$
\sum_{i}^{N} (y_i - (c_1 x_i + c_0))^2
$$

1

*N*

One way to minimize our objective function  $J(c_1, c_0)$  is with **gradient descent**.

them based on **how much they contribute to the error**

To update these coefficients, we can subtract their contribution to the error:

## We can initialize our coefficients with random values, and adjust

$$
c_i := c_i - \epsilon \frac{\partial J(c)}{\partial c_i}
$$

- $c_i := c$
- Where  $\epsilon$  is the step size in the direction of error. For stable adjustments, we want this to be small. For a linear model:

 $J(c_1, c_0) =$ 1 *N* ∂*J*(*c*) 1 *d* ∂*ci* = *N dci*

$$
c_i - \epsilon \frac{\partial J(c)}{\partial c_i}
$$

$$
\sum_{i}^{N} (y_i - (c_1 x_i + c_0))^2
$$
  

$$
-\sum_{i}^{N} (y_i - c_1 x_i - c_0)^2
$$

- $J(c_1, c_0) =$ 1 *N*
- ∂*J*(*c*)  $\partial c_n$ = 1 *N d dcn*
- $c_1 := c_1 \epsilon$  $\overline{\phantom{a}}$  $-\frac{2}{\sqrt{2}}$ *N*
- $c_0 := c_0 \epsilon \left| -\frac{2}{\lambda} \right|$

*N* ∑ *i*  $(y_i - (c_1 x_i + c_0))$ 2



$$
\left[\sum_{i}^{N}\left(y_{i}-c_{1}x_{i}-c_{0}\right)x_{i}\right]
$$

$$
\frac{2}{N} \sum_{j}^{N} \left( y_j - c_1 x_j - c_0 \right)
$$

### **Curve Fitting |** Linear Regressions Let's try a **linear regression** on an Order-1 dataset with step-size 0.1:



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What's happening here?

Our **step size** is far too large, and our steps away from the objective function overcompensate each coefficient's contribution!



What about a step size of 0.01:



- 
- 

#### What about a step size of 0.01:



- 
- 

#### What about a step size of 0.01:



- 
- 

#### After only **3 passes** of our data, our model has a great fit!



We can generalize this approach to systems of **higher degrees** as well!

We take the same approach for updating coefficients of higher degrees:

 $J(c_2, c_1, c_0) =$ 1 *N N* ∑ *i*

$$
c_2 := c_2 - \epsilon \left[ -\frac{2}{N} \sum_{i}^{N} \left( y_i - c_2 x_i^2 - c_1 x_i - c_0 \right) x_i^2 \right]
$$

$$
(y_i - (c_2 x_i^2 + c_1 x_i + c_0))^2
$$

#### In this example we take a **5th degree** linear regression on a noisy **1st degree** dataset:



complex enough to directly touch each datapoint, we'll converge on  $R^2 = 1$ 

But we know this is bad because our data often contains **noise**!

- Although we have a high  $R^\angle$ , and potentially a lot higher than the linear fit if we keep training, the model is **not generalizable**
- If we train and test on the same data, and our model is infinitely 4.0





*R*2

### This phenomenon is known as **overfitting**, and when we only train a model on the same **training data**, we're fitting it to that





dataset, and not the system that it comes from

Therefore, we must evaluate the model on data we **did not train on**

We need to **dissuade our model from overfitting**

### **Curve Fitting |** Overfitting

### To prevent **overfitting** and keep our model generalizable, we have to tune the degree of our model to the shape of the data,

and how much data we have (**hyperparameter tuning**)



### **Curve Fitting |** Overfitting

#### **Curve Fitting |** Overfitting



### **Curve Fitting |** Machine Learning

testing data

Although the 10th-order model had a better  $R^2$  than the 2nd-Order  $\overline{R}$ on the training set, it performed much worse when exposed to new *R*2

The ultimate goal of regression is to create a model that particular range by using a lower order model)

- hypothesizes the behavior of a system (maybe even linearizes a
- dimensionality to fit the noise instead of the data, which will **not**

The higher order data may end up using much of its "extra" generalize well as we introduce more data!